

# Table of Contents

## Best Student Paper

- A Robust Speech Recognition System for Service-Robotics Applications ..... 1  
*Masrur Doostdar, Stefan Schiffer, and Gerhard Lakemeyer*

## Papers with Oral Presentation

- Intuitive Humanoid Motion Generation Joining User-Defined Key-Frames and Automatic Learning ..... 13  
*Marco Antonelli, Fabio Dalla Libera, Emanuele Menegatti, Takashi Minato, and Hiroshi Ishiguro*
- Landmark-Based Representations for Navigating Holonomic Soccer Robots ..... 25  
*Daniel Beck, Alexander Ferrein, and Gerhard Lakemeyer*
- Mutual Localization in a Team of Autonomous Robots Using Acoustic Robot Detection ..... 37  
*David Becker and Max Risler*
- Tracking of Ball Trajectories with a Free Moving Camera-Inertial Sensor ..... 49  
*Oliver Birbach, Jörg Kurlbaum, Tim Laue, and Udo Frese*
- A Case Study on Improving Defense Behavior in Soccer Simulation 2D: The NeuroHassle Approach ..... 61  
*Thomas Gabel, Martin Riedmiller, and Florian Trost*
- Constraint Based Belief Modeling ..... 73  
*Daniel Göhring, Heinrich Mellmann, and Hans-Dieter Burkhardt*
- Explicitly Task Oriented Probabilistic Active Vision for a Mobile Robot ..... 85  
*Pablo Guerrero, Javier Ruiz-del-Solar, and Miguel Romero*
- An Incremental SLAM Algorithm with Inter-calibration between State Estimation and Data Association ..... 97  
*Xiucui Ji, Hui Zhang, Dan Hai, and Zhiqiang Zheng*
- Development of an Augmented Environment and Autonomous Learning for Quadruped Robots ..... 109  
*Hayato Kobayashi, Tsugutoyo Osaki, Tetsuro Okuyama, Akira Ishino, and Ayumi Shinohara*

## XII Table of Contents

Automatic Parameter Optimization for a Dynamic Robot Simulation . . . . .	121
<i>Tim Laue and Matthias Hebbel</i>	
Arbitrary Ball Recognition Based on Omni-Directional Vision for Soccer Robots . . . . .	133
<i>Huimin Lu, Hui Zhang, Junhao Xiao, Fei Liu, and Zhiqiang Zheng</i>	
A Robust Statistical Collision Detection Framework for Quadruped Robots . . . . .	145
<i>Tekin Meriçli, Çetin Meriçli, and H. Levent Akin</i>	
Increasing Foot Clearance in Biped Walking: Independence of Body Vibration Amplitude from Foot Clearance . . . . .	157
<i>Hamid Reza Mabalagh, Mojgan Mohajer, and Raul Rojas</i>	
Adapting ADDIE Model for Human Robot Interaction in Soccer Robotics Domain . . . . .	166
<i>Rajesh Elara Mohan, Carlos A. Acosta Calderon, Changjiu Zhou, Tianwu Yang, Liandong Zhang, and Yongming Yang</i>	
A Proposal of Bridging Activities between RoboCupJunior and Senior Leagues . . . . .	177
<i>Yasunori Nagasaka, Tatsumasa Kitahara, and Tomoichi Takahashi</i>	
A Collaborative Multi-robot Localization Method without Robot Identification . . . . .	189
<i>Nezih Ergin Özkucur, Barış Kurt, and H. Levent Akin</i>	
Teamwork Design Based on Petri Net Plans . . . . .	200
<i>Pier Francesco Palamara, Vittorio A. Ziparo, Luca Iocchi, Daniele Nardi, and Pedro Lima</i>	
Bayesian Spatiotemporal Context Integration Sources in Robot Vision Systems . . . . .	212
<i>Rodrigo Palma-Amestoy, Pablo Guerrero, Javier Ruiz-del-Solar, and C. Garreton</i>	
Towards Cooperative and Decentralized Mapping in the Jacobs Virtual Rescue Team . . . . .	225
<i>Max Pfingsthorn, Yashodhan Nevatia, Todor Stoyanov, Ravi Rathnam, Stefan Markov, and Andreas Birk</i>	
Robust Supporting Role in Coordinated Two-Robot Soccer Attack . . . . .	235
<i>Mike Phillips and Manuela Veloso</i>	
A Novel Approach to Efficient Error Correction for the SwissRanger Time-of-Flight 3D Camera . . . . .	247
<i>Jann Poppinga and Andreas Birk</i>	

Autonomous Evolution of High-Speed Quadruped Gaits Using Particle Swarm Optimization .....	259
<i>Chunxia Rong, Qining Wang, Yan Huang, Guangming Xie, and Long Wang</i>	
Designing Fall Sequences That Minimize Robot Damage in Robot Soccer .....	271
<i>Javier Ruiz-del-Solar, Rodrigo Palma-Amestoy, Paul Vallejos, R. Marchant, and P. Zegers</i>	
The Use of Scripts Based on Conceptual Dependency Primitives for the Operation of Service Mobile Robots .....	284
<i>Jesus Savage, Alfredo Weitzenfeld, Francisco Ayala, and Sergio Cuellar</i>	
An Omnidirectional Camera Simulation for the USARSim World.....	296
<i>Tijn Schmits and Arnoud Visser</i>	
Introducing Image Processing to RoboCupJunior: PALB VISION A First Implementation of Live Image Processing in RCJ Soccer .....	308
<i>Christoph Siedentop, Max Schwarz, and Sebastian Pfülb</i>	
Multi-robot Range-Only SLAM by Active Sensor Nodes for Urban Search and Rescue .....	318
<i>Dali Sun, Alexander Kleiner, and Thomas M. Wendt</i>	
Analysis Methods of Agent Behavior and Its Interpretation in a Case of Rescue Simulations .....	331
<i>Tomoichi Takahashi</i>	
Spiral Development of Behavior Acquisition and Recognition Based on State Value .....	343
<i>Yasutake Takahashi, Yoshihiro Tamura, and Minoru Asada</i>	
Determining Map Quality through an Image Similarity Metric .....	355
<i>Ioana Varsadan, Andreas Birk, and Max Pfingsthorn</i>	
Real-Time Spatio-Temporal Analysis of Dynamic Scenes in 3D Soccer Simulation .....	366
<i>Tobias Warden, Andreas D. Lattner, and Ubbo Visser</i>	
Coaching Robots to Play Soccer via Spoken-Language .....	379
<i>Alfredo Weitzenfeld, Carlos Ramos, and Peter Ford Dominey</i>	
Player Positioning in the Four-Legged League .....	391
<i>Henry Work, Eric Chown, Tucker Hermans, Jesse Butterfield, and Mark McGranaghan</i>	

Humanoid Robot Gait Generation Based on Limit Cycle Stability . . . . .	403
<i>Mingguo Zhao, Ji Zhang, Hao Dong, Yu Liu, Liguo Li, and Xuemin Su</i>	
Playing Creative Soccer: Randomized Behavioral Kinodynamic Planning of Robot Tactics . . . . .	414
<i>Stefan Zickler and Manuela Veloso</i>	
<b>Papers with Poster Presentation</b>	
A Robot Referee for Robot Soccer . . . . .	426
<i>Matías Arenas, Javier Ruiz-del-Solar, Simón Norambuena, and Sebastián Cubillos</i>	
Detection of Basic Behaviors in Logged Data in RoboCup Small Size League . . . . .	439
<i>Koshi Asano, Kazuhito Murakami, and Tadashi Naruse</i>	
Using Different Humanoid Robots for Science Edutainment of Secondary School Pupils . . . . .	451
<i>Andreas Birk, Jann Poppinga, and Max Pfingsthorn</i>	
Planetary Exploration in USARsim: A Case Study Including Real World Data from Mars . . . . .	463
<i>Andreas Birk, Jann Poppinga, Todor Stoyanov, and Yashodhan Nevatia</i>	
Face Recognition for Human-Robot Interaction Applications: A Comparative Study . . . . .	473
<i>Mauricio Correa, Javier Ruiz-del-Solar, and Fernando Bernuy</i>	
xROB-S and iCon-X: Flexible Hardware, Visual Programming and Software Component Reuse . . . . .	485
<i>Stefan Enderle, Wolfgang Günther, Hans-Juergen Hilscher, and Holger Kenn</i>	
Multi-level Network Analysis of Multi-agent Systems . . . . .	495
<i>Pejman Iravani</i>	
A Decision-Theoretic Active Loop Closing Approach to Autonomous Robot Exploration and Mapping . . . . .	507
<i>Xiucai Ji, Hui Zhang, Dan Hai, and Zhiqiang Zheng</i>	
Domestic Interaction on a Segway Base . . . . .	519
<i>W. Bradley Knox, Juhyun Lee, and Peter Stone</i>	
Combining Policy Search with Planning in Multi-agent Cooperation . . . . .	532
<i>Jie Ma and Stephen Cameron</i>	

Model-Free Active Balancing for Humanoid Robots . . . . .	544
<i>Sara McGrath, John Anderson, and Jacky Baltes</i>	
Stereo-Vision Based Control of a Car Using Fast Line-Segment Extraction . . . . .	556
<i>Brian McKinnon, Jacky Baltes, and John Anderson</i>	
A Layered Metric Definition and Evaluation Framework for Multirobot Systems . . . . .	568
<i>Çetin Meriçli and H. Levent Akin</i>	
RobotStadium: Online Humanoid Robot Soccer Simulation Competition . . . . .	580
<i>Olivier Michel, Yvan Bourquin, and Jean-Christophe Baillie</i>	
Real-Time Simulation of Motion-Based Camera Disturbances . . . . .	591
<i>Dennis Pachur, Tim Laue, and Thomas Röfer</i>	
Database Driven RoboCup Rescue Server . . . . .	602
<i>Rahul Sarika, Harith Siddhartha, and Kamalakar Karlapalem</i>	
What Motion Patterns Tell Us about Soccer Teams . . . . .	614
<i>Jörn Sprado and Björn Gottfried</i>	
Designing Grounded Agents: From RoboCup to the Real-World . . . . .	626
<i>Christopher Stanton</i>	
Robust Moving Object Detection from a Moving Video Camera Using Neural Network and Kalman Filter . . . . .	638
<i>Sanaz Taleghani, Siavash Aslani, and Saeed Shiry</i>	
Collaborative Localization Based Formation Control of Multiple Quadruped Robots . . . . .	649
<i>Qining Wang, Hua Li, Feifei Huang, Guangming Xie, and Long Wang</i>	
<b>Author Index . . . . .</b>	<b>661</b>